## Athindran Ramesh Kumar

r.athindran@gmail.com Pittsburgh, PA Webpage: https://athindran.github.io/

### OUTLINE

Domain expertise in machine learning and robotics. Focus of PhD is on safety certification using optimization, learning and control. Taught several courses on machine learning, deep learning and data science as a TA.

EDUCATION	
Princeton University	NJ, USA
MA + PhD, Electrical and Computer Engineering	Sep.2018 - Sep 2023
Advisor: Prof. Peter J. Ramadge	GPA: 3.93/4.0
<ul> <li>Key Courses: Machine learning and Pattern Recognition, Modern Control, Safe Ro Learning, Optimization for Machine Learning, Reinforcement Learning.</li> <li>M.A. degree in Electrical Engineering awarded.</li> <li>Ph.D. dissertation not complete. Other requirements met and retained candidacy.</li> </ul>	botics, Theoretical Machine
University of Illinois at Urbana-Champaign	Illinois, USA
MS (fully funded by Dept.), Electrical and Computer Engineering	Aug. 2013 - Aug 2015
Advisor: Prof. Grace Gao	GPA: 3.95/4.0
• Key Courses: GNSS systems, Computer Vision, Convex Optimization.	
Indian Institute of Technology, Madras	Chennai, India
B. Tech, Electrical Engineering	Aug. 2009 - July 2013
Advisor: Prof. Radhakrishna Ganti	GPA : 9.27/10.0

## SELECT PUBLICATIONS \_

#### Journal Papers

- A.R. Kumar, K. -C. Hsu, P. J. Ramadge and J. F. Fisac, "Fast, Smooth, and Safe: Implicit Control Barrier Functions through Reach-Avoid Differential Dynamic Programming," in IEEE Control Systems Letters, doi: 10.1109/LCSYS.2023.3292132.
- Heng, Liang, A.R. Kumar, and Grace Gao. "Private proximity detection using partial GPS information." IEEE Transactions on Aerospace and Electronic Systems 52.6 (2016): 2873-2885.

#### **Conference and Workshop Papers**

- S. Liu, A.R. Kumar, Jaime F. Fisac, Ryan P. Adams, Peter J. Ramadge. "ProBF: Probabilistic Safety Certificates with Barrier Functions." Presented at SafeRL workshop at NeurIPS 2021.
- A.R. Kumar and Peter J. Ramadge. "Learning to Control Using a Convex Combination of Controllers." 2021 American Control Conference (ACC). IEEE, 2021.
- A.R. Kumar and Peter J. Ramadge, 2021, March. DiffLoop: "Tuning PID controllers by differentiating through the feedback loop." In 2021 55th Annual Conference on Information Sciences and Systems (CISS) (pp. 1-6). IEEE.
- T. H. Fan, A. R. Kumar and P. J. Ramadge. Safety Control for Prime Focus Spectrograph. In 2022 56th Annual Conference on Information Sciences and Systems (CISS) (pp. 269-274). IEEE.
- A.R. Kumar, Balaraman Ravindran, and Anand Raghunathan. "Pack and detect: Fast object detection in videos using region-of-interest packing." Proceedings of the ACM India Joint International Conference on Data Science and Management of Data. 2019.
- A.R. Kumar, Liang Heng, and Grace X. Gao. "GPS privacy: Enabling proximity-based services while keeping GPS location private." Proceedings of the 27th International Technical Meeting of the Satellite Division of the Institute of Navigation (ION GNSS+ 2013),(Tampa, FL). 2014.

#### Patents

• Athindran R, Navinnath P, Klutto Milleth, Bhaskar Ramamurthi, "Frequency Assignment for SINR and Throughput Management in Battlefield Communication", India Patent granted 27th June 2024.

#### SELECT ACADEMIC ACHIEVEMENTS

- Awarded full-tuition waiver and stipend for MS degree program at University of Illinois, Urbana-Champaign.
- Received first-year fellowship at Princeton University for PhD program.
- Outstanding merit in Mathematics from Srinivas Ramanujan academy of Maths talent awarded in 2008.
- Ranked 294 out of 1,000,000 students in AIEEE and 1561 out of 800,000 students in JEE.

# PROFESSIONAL EXPERIENCE \_\_\_\_\_

Aurora Tech     Software Engineer II - L5 Engineer	Pittsburgh, PA October 2023 - present
<ul><li>Software Engineer in Control until October 2024.</li><li>ML Software Engineer currently working on transformer models :</li></ul>	for scene forecasting.
Nokia Bell Labs     Research Intern	Murray Hill, NJ Jun - Aug 2021
• Reinforcement learning algorithms for a multi-link robotic arm in	simulation.
• Center of Excellence in Wireless Technology Research Engineer	Chennai, India Apr 2016 - June 2018
• Frequency planning in a communication system.	
• IIT Madras Project Associate	Chennai, India Nov 2015 - Mar 2016, Jul 2017 - Jul 2018
<ul><li>Wrote a proposal seeking funding for the 5G mmWave cellular pr</li><li>Efficient deep learning for video processing.</li></ul>	roject at IIT Madras.
• Google Inc.	Mountain View, CA
Software Intern - Street View	May - Aug 2014
• Implemented ambiguity resolution algorithms in Python on GPS on Street View cars to achieve sub-meter accurate positioning.	carrier phase data obtained from receivers installed
<ul> <li>Conferences: ICLR (2021, 2023, 2024), NeurIPS (2022-2024), I</li> <li>Journals: IEEE Transactions on Control Systems Technology,</li> <li>Top reviewer for NeurIPS 2023.</li> </ul>	CML (2023-2025), CISS 2022, IJCAI 2024. IEEE Robotics and Automation Letters.
SELECT PROJECTS	Control– Princeton University, NJ
Guide: Prof. Peter Ramadge	Jul 2019 - Aug 2023
<ul><li>Safety certification for autonomous control systems.</li><li>Learning residual dynamics using probabilistic models.</li></ul>	
-Efficient Deep Learning for Videos-	IIT Madras, Chennai
Guide: Prof. B. Ravindran and Prof. Anand Raghunathan (Pure	lue University) Jul 2017 - Jul 2018
<ul> <li>Novel inference time method to accelerate object detection in video</li> <li>Published ACM India Joint International Conference on Date</li> </ul>	s. ta Science and Management of Data 2019.
-Direct Position Tracking using the Vector Correlator- Guide: Prof. Grace Gao	University of Illinois, Urbana-Champaign $Aug \ 2014$ - $Aug \ 2015$
• Proposed a novel direct position tracking loop for GPS using the U	nscented Kalman Filter (UKF).
-Object recognition at a road intersection-	University of Ulm, Germany
Guide: Dr. Klaus Dietmayer	Apr 2012 - Aug 2012
• Developed a labeling tool used by the Ko-FAS team for sensor data <b>PROGRAMMING SKILLS</b>	fusion.
- Python - PyTorch - JAX - C++ - Te	nsorflow - Matlab